

Lecture Notes for Math 210 – 26 October 2007

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Chapter 5: Tools in Probability Theory

Conditional Probability and Conditional Expectation for Continuous Random Variables

Suppose X is a random variable.

The c.d.f. of X is a function $F : \mathbb{R} \rightarrow [0, 1]$, defined as

$$F_X(a) = \mathbf{P}\{X \leq a\}.$$

(I'm changing notation to $F_X(a)$ instead of $G_X(a)$.)

Then X is called a continuous random variable if

$$f_X(x) = \frac{d}{dx}F_X(x),$$

exists at “almost all” points $x \in \mathbb{R}$, and if

$$F_X(a) = \int_{-\infty}^a f_X(x) dx,$$

at *all* points $a \in \mathbb{R}$.

Example 1. The exponential random variable with “rate” $\lambda > 0$ is defined as X such that

$$F_X(a) = \begin{cases} 0 & \text{if } a < 0, \\ 1 - e^{-\lambda a} & \text{if } a \geq 0. \end{cases}$$

Then note that

$$\frac{d}{dx}F_X(x) = \begin{cases} 0 & \text{if } x < 0, \\ \text{D.N.E.} & \text{if } x = 0, \\ \lambda e^{-\lambda x} & \text{if } x > 0. \end{cases}$$

So it is impossible to say the value of $f_X(0)$ from the derivative of $F_X(x)$.

Related to this, there is a jump discontinuity in $f_X(x)$ of size λ at $x = 0$.

But, no matter what value we plug in for $f_X(0)$, we *do* have

$$\int_{-\infty}^a f_X(x) dx = 0 = F_X(a) \quad \text{if } a \leq 0,$$

and, for $a \geq 0$,

$$\int_{-\infty}^a f_X(x) dx = \int_0^a \lambda e^{-\lambda x} dx = -e^{-\lambda x} \Big|_0^a = -e^{-\lambda a} + 1 = F_X(a).$$

The reason is that 1 single value of $f_X(x)$ does not change the integral.

So the fact that $f_X(0)$ is not clearly specified is not a problem.

For a continuous random variable, $f_X(x)$ is called the probability density function, p.d.f.

Joint distributions:

Remember that random variables X and Y are defined as functions from some sample space Ω to \mathbb{R} .

Suppose that there is an event space \mathcal{F} such that both X and Y are \mathcal{F} -measurable.

Also suppose there is a probability “measure” $P : \mathcal{F} \rightarrow \Omega$.

Then we define the joint c.d.f. of X and Y as

$$F_{X,Y}(a, b) = \mathbf{P}\{X \leq a, Y \leq b\}.$$

We say that X and Y are jointly continuous if there is a function $f_{X,Y}(x, y)$ such that

$$F_{X,Y}(a, b) = \int_{-\infty}^a \int_{-\infty}^b f_{X,Y}(x, y) dx dy,$$

for all $a, b \in \mathbb{R}$.

(Then one knows that $f_{X,Y}(x, y) = \frac{\partial}{\partial x}(\frac{\partial}{\partial y}(F_{X,Y}(x, y)))$ at “almost all” points x and y .)

One defines the marginal distributions as

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy,$$

which is a p.d.f. for X , alone, and similarly for Y .

The conditional p.d.f. for X , given Y , is then defined as

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x, y)}{f_Y(y)},$$

which is defined everywhere that $f_Y(y) \neq 0$.

Then, at least heuristically, one should expect that

$$\mathbf{E}[X | Y] = g(Y),$$

where

$$g(y) = \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx.$$

We just write this as

$$\mathbf{E}[X | \{Y = y\}] = \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx.$$

More generally, we expect that for any function $h(x)$

$$\mathbf{E}[h(X) | \{Y = y\}] = \int_{-\infty}^{\infty} h(x) f_{X|Y}(x|y) dx.$$

This formula is basically true, although one has to be somewhat careful if $f_Y(y)$ is ever 0.

We will skip the technicalities necessary to make this rigorous.

Example. A preliminary definition of Brownian motion is a family of random variables Z_t , defined for all $t \geq 0$, such that $Z_0 = 0$, and for every $0 \leq s < t$, the increment $[Z_t - Z_s]$ is a normal random variable, with mean 0 and variance equal to $t - s$, which is independent of all Z_r with $r \leq s$.

Q: Find $f_{Z_s|Z_t}(x, y)$, for $s < t$.

Let us start by calculating $f_{Z_s, Z_t}(x, y)$.

It will actually be easier to start by calculating $f_{Z_s, Z_t}(x, x + y)$, and then substitute

$y - x$ for y .

The reason is that we know Z_s by itself is a normal random variable with variance s :

$$f_{Z_s}(x) = \frac{e^{-\frac{x^2}{2s}}}{\sqrt{2\pi s}}.$$

But also, $Z_t - Z_s$ is independent of Z_s and it is normal with variance $t - s$:

$$f_{Z_t - Z_s}(y) = \frac{e^{-\frac{y^2}{2(t-s)}}}{\sqrt{2\pi(t-s)}}.$$

From this we can deduce that

$$f_{Z_s, Z_t}(x, x + y) = f_{Z_s}(x) \cdot f_{Z_t - Z_s}(y) = \frac{1}{2\pi\sqrt{s(t-s)}} e^{-\frac{x^2}{2s} - \frac{y^2}{2(t-s)}}.$$

So,

$$f_{Z_s, Z_t}(x, y) = \frac{1}{2\pi\sqrt{s(t-s)}} e^{-\frac{x^2}{2s} - \frac{(y-x)^2}{2(t-s)}}.$$

We also know that Z_t by itself is normal with variance t :

$$f_{Z_t}(y) = \frac{e^{-\frac{y^2}{2t}}}{\sqrt{2\pi t}}.$$

So,

$$\begin{aligned} f_{Z_s|Z_t}(x|y) &= \frac{f_{Z_s, Z_t}(x, y)}{f_{Z_t}(y)} \\ &= \frac{\sqrt{2\pi t}}{2\pi\sqrt{s(t-s)}} e^{-\frac{x^2}{2s} - \frac{(y-x)^2}{2(t-s)} + \frac{y^2}{2t}}. \end{aligned}$$

By expanding the quadratic functions in the exponent, you get

$$f_{Z_s|Z_t}(x|y) = \frac{1}{\sqrt{2\pi[s(t-s)/t]}} e^{-\frac{t}{2s(t-s)}\left[x-\frac{s}{t}y\right]^2}.$$

In other words, if we condition Brownian motion at time s on Brownian motion Z_t at time t , then the conditioned random variable is normally distributed but with mean $\frac{s}{t}Z_t$ and variance $\frac{s(t-s)}{t}$.

Or to put it yet another way: if we want to simulate a finite dimensional approximation to Brownian motion on the interval $[0, T]$, we can start by simulating Z_T by a normal random variable, then we can fill in $Z_{T/2}$ by taking the conditional probability as stated above. Then we can iteratively fill-in the picture by taking $Z_{T/4}$ and $Z_{2T/4}$ and so, on, splitting each subinterval in half at each step of the iteration.