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# A canonical operad pair 

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1. Introduction. The purpose of this paper is to construct an operad $\mathscr{H}_{\infty}$ with the good properties of both the little convex bodies partial operad $\mathscr{K}_{\infty}$ and the little cubes operad $\mathscr{C}_{\infty}$ used in May's theory of $E_{\infty}$ ring spaces or multiplicative infinite loop spaces ((6), chapter VII). In (6) $\mathscr{H}_{\infty}$ can then be used instead of $\mathscr{K}_{\infty}$ and $\mathscr{C}_{\infty}$, and the theory becomes much simpler; in particular all partial operads can be replaced by genuine ones. The method used here is a modification of that which May suggests on (6), page 170, but cannot carry out.

We shall use various spaces associated to a finite-dimensional real inner product space $V$. First, let $\mathscr{A} V$ be the space of all topological embeddings of $V$ in itself. Next, for $k=0,1,2, \ldots$, let $\mathscr{D}_{V}(k)$ be the subspace of $(\mathscr{A} V)^{k}$ consisting of $k$-tuples of embeddings with disjoint images; by convention $\mathscr{D}_{V}(0)=*$, a point. Finally, let $F(V, k)$ be the $k$ th configuration space of $V$; it consists of $k$-tuples of distinct points of $V$, with $F(V, 0)=$ * also.

The pair $(\mathscr{A}, \mathscr{D})$ has a complicated structure: $\mathscr{A} V$ is a monoid under composition, there is a direct product map from $\mathscr{A} V \times \mathscr{A} W$ to $\mathscr{A}(V \oplus W)$ inducing a map from $\mathscr{D}_{V}(k) \times \mathscr{D}_{W}(l)$ to $\mathscr{D}_{V \oplus W}(k l)$, and so on. We shall sum this up by saying that $(\mathscr{A}, \mathscr{D})$ is an object in a category $\Phi$, to be defined in Section 2 below.

The symmetric group $\Sigma_{k}$ acts on $F(V, k)$ and $\mathscr{D}_{V}(k)$; in Section 3 we shall construct a $\Sigma_{k}$-equivariant map

$$
\theta: F(V, k) \rightarrow \mathscr{D}_{V}(k) .
$$

For $\left(v_{1}, \ldots, v_{k}\right)$ a point of $F(V, k)$ we shall have

$$
\theta\left(v_{1}, \ldots, v_{k}\right)=\left(c_{1}, \ldots, c_{k}\right)
$$

where $c_{r}$ embeds $V$ onto some open ball with centre $v_{r}$ in an orientation-preserving way; the complete definition of $\theta$ does not add anything important to this information.

We can now state the main theorem of this paper.
Theorem. There is an object ( $\mathscr{E}, \mathscr{H}$ ) of the category $\Phi$, a morphism $\pi:(\mathscr{E}, \mathscr{H}) \rightarrow(\mathscr{A}, \mathscr{D})$, and maps $\phi: F(V, k) \rightarrow \mathscr{H}_{V}(k)$ making $F(V, k) \Sigma_{k}$-equivariantly homotopy equivalent to $\mathscr{H}_{V}(k)$ such that

$$
\pi \phi=\theta: F(V, k) \rightarrow \mathscr{D}_{V}(k)
$$

The proof is given in Section 4.
The difference from the programme suggested on (6), page 170 is that $\mathscr{E} V$ is not a subspace of $\mathscr{A} V$. This does not affect the applications to iterated loop space theory; see Section 5.
2. The category $\Phi$. Let $\mathscr{I}_{*}$ be the category of finite-dimensional real inner product spaces and isometric linear isomorphisms. An object $(\mathscr{A}, \mathscr{D})$ of $\Phi$ then consists of the following:
(a) a continuous functor $\mathscr{A}$ from $\mathscr{I}_{*}$ to topological monoids;
(b) subfunctors $\mathscr{D}_{(-)}(k)$ of $\mathscr{A}(-)^{k}$ for $k=0,1,2, \ldots$, with $\mathscr{D}_{V}(0)=*$ for all $V$;
(c) a continuous commutative and associative natural transformation

$$
(c, d) \mapsto c \times d: \mathscr{A} V \times \mathscr{A} W \rightarrow \mathscr{A}(V \oplus W)
$$

of functors from $\mathscr{I}_{*} \times \mathscr{I}_{*}$ to topological monoids.
The following axioms must hold:
(1) the maps $c \mapsto c \times 1: \mathscr{A} V \rightarrow \mathscr{A}(V \oplus\{0\})=\mathscr{A} V$ are identity maps;
(2) the maps $c \mapsto c \times 1: \mathscr{A} V \rightarrow \mathscr{A}(V \oplus W)$ are closed inclusions;
(3) the spaces $\mathscr{D}_{V}(k)$ are invariant under the action of $\Sigma_{k}$ on $(\mathscr{A} V)^{k}$;
(4) $1 \in \mathscr{D}_{V}(1)$ for all $V$;
(5) if $\left(c_{r}: 1 \leqslant r \leqslant k\right) \in \mathscr{D}_{V}(k)$ and $\left(d_{r s}: 1 \leqslant s \leqslant j_{r}\right) \in \mathscr{D}_{V}\left(j_{r}\right)$ for $1 \leqslant r \leqslant k$, then

$$
\left(c_{r} d_{r s}: 1 \leqslant r \leqslant k, 1 \leqslant s \leqslant j_{r}\right) \in \mathscr{D}_{V}\left(j_{1}+\ldots+j_{r}\right)
$$

(6) if $\left(c_{r}: 1 \leqslant r \leqslant k\right) \in \mathscr{D}_{V}(k)$ and $\left(d_{s}: 1 \leqslant s \leqslant l\right) \in \mathscr{D}_{W}(l)$, then

$$
\left(c_{r} \times d_{s}: 1 \leqslant r \leqslant k, 1 \leqslant s \leqslant l\right) \in \mathscr{D}_{V \oplus W}(k l) .
$$

The morphisms of $\Phi$ are natural transformations of $\mathscr{A}$ inducing natural transformations of the $\mathscr{D}_{(-)}(k)$ and preserving all the structure.

Given (a) and (c), the axioms (1) and (2) say that $\mathscr{A}$ is an $\mathscr{I}_{*}$-monoid in the sense of (5), $1 \cdot 1$. By the method described in (6), $\mathrm{I} \cdot 1$, one can extend $\mathscr{A}$, and with it the $\mathscr{D}_{(-)}(k)$, to the category $\mathscr{I}$ of finite- or countable-dimensional real inner product spaces and linear isometries (which need not be surjective). First, if $f: V \rightarrow W$ is an isometry between finite-dimensional spaces, then $W$ is an orthogonal direct sum,

$$
W=f V \oplus X
$$

say, and $f$ induces an isomorphism $f^{\prime}: V \rightarrow f V$. We define $\mathscr{A} f: \mathscr{A} V \rightarrow \mathscr{A} W$ by

$$
(\mathscr{A} f)(c)=\left(\mathscr{A} f^{\prime}\right)(c) \times 1 \quad \text { for } \quad c \in \mathscr{A} V
$$

For a countable-dimensional space $V$ we then set

$$
\mathscr{A} V=\operatorname{colim}_{W} \mathscr{A} W
$$

where $W$ runs through the finite-dimensional subspaces of $V$. Similarly we extend the $\mathscr{D}_{(-)}(k)$ and the direct product natural transformation of (c) by colimits. Axioms (1)-(6) still hold for these extended structures.

It is easy to see that the pair $(\mathscr{A}, \mathscr{D})$ of Section 1, consisting of embeddings and embeddings with disjoint images, is an object of $\Phi$. We use composition to make $\mathscr{A} V$ a monoid; if $f: V \rightarrow W$ is an isometric isomorphism, then $(\mathscr{A} f)(c)=f c f^{-1}$ for $c \in \mathscr{A} V$; the natural transformation of $(c)$ is given by the direct product of functions; and the axioms are easily verified.
3. The $\operatorname{map} \theta: F(V, k) \rightarrow \mathscr{D}_{V}(k)$. In this section, as in Section 1, $V$ is a finite-dimensional real inner product space, $F(V, k)$ is the $k$ th configuration space of $V$, and $\mathscr{D}_{V}(k)$
is the space of $k$-tuples of embeddings of $V$ in $V$ with disjoint images. We construct a $\Sigma_{k}$-equivariant map $\theta: F(V, k) \rightarrow \mathscr{D}_{V}(k)$ as follows.

Given $\left(v_{1}, \ldots, v_{k}\right)$ in $\boldsymbol{F}(V, k)$, let $\rho$ be

$$
\frac{1}{2} \min \left\{\left\|v_{r}-v_{s}\right\|: r \neq s\right\}
$$

(taken as $\infty$ if $k=1$ ), so $\rho$ is in $(0, \infty]$ and depends continuously on $\left(v_{1}, \ldots, v_{k}\right)$. Define a continuous function $e_{\rho}: V \rightarrow V$ by

$$
e_{\rho} x=\frac{\rho x}{\rho+\|x\|} \quad \text { for } \quad x \in V
$$

Then $\theta\left(v_{1}, \ldots, v_{k}\right)$ is to be $\left(c_{1}, \ldots, c_{k}\right)$ where $c_{r}: V \rightarrow V$ is given by

$$
c_{r}(x)=v_{r}+e_{\rho} x \quad \text { for } \quad x \in V
$$

It is obvious that $\left\|e_{\rho} x\right\|<\rho$, so $c_{r}(x)$ is within $\rho$ of $v_{r}$ for all $x$. Since distinct $v_{r}$ are at least $2 \rho$ apart, the $c_{r}$ must have disjoint images.

To justify this construction, we must show that the $c_{r}$ are embeddings, or equivalently that $e_{\rho}$ is an embedding. For use in the next section we give a more general result.

Lemma. Let $a$ and $b$ be non-negative real numbers with $a+b=1$ and define $f: V \rightarrow V$ by

$$
f(x)=a e_{\rho} x+b x \quad \text { for } \quad x \in V
$$

Then $f$ is a distance-reducing embedding.
Here distance-reducing means that $\|f(x)-f(y)\| \leqslant\|x-y\|$ for $x$ and $y$ in $V$.
Proof. We use differential calculus. By computation, $f$ is differentiable everywhere, and

$$
\begin{aligned}
D f(x)(y) & =\left[a\left(\frac{\rho}{\rho+\|x\|}\right)+b\right] y \quad \text { if } \quad\langle x, y\rangle=0 \\
& =\left[a\left(\frac{\rho}{\rho+\|x\|}\right)^{2}+b\right] y \quad \text { if } \quad x \text { and } y \text { are linearly dependent. }
\end{aligned}
$$

So $D f(x)$ is diagonalizable with respect to an orthonormal base and its eigenvalues lie in $(0,1]$. Since $D f(x)$ is everywhere non-singular, $f$ is an embedding by Rolle's theorem; since $\|D f(x)\| \leqslant 1$ everywhere, $f$ is distance-reducing by the mean-value theorem. This completes the proof.
4. Proof of the theorem. Let $V$ be a finite-dimensional real inner product space. Then $\mathscr{E} V$ is to be the space of maps

$$
h:[0,1] \rightarrow \mathscr{A} V
$$

such that $h(t)$ is a distance-reducing embedding for all $t$ and such that $h(1)$ is the identity. For $k \geqslant 1, \mathscr{H}_{V}(k)$ is to be the space of $k$-tuples $\left(h_{1}, \ldots, h_{k}\right)$ in $(\mathscr{E} V)^{k}$ such that the $h_{r}(0)$ have disjoint images. The various products in $\mathscr{E} V$ are to be induced by the corresponding products in $\mathscr{A} V$; it is then easy to see that $(\mathscr{E}, \mathscr{H})$ is an object of $\Phi$. And $\pi: \mathscr{E} V \rightarrow \mathscr{A} V$ is to be given by

$$
\pi(h)=h(0)
$$

it is easy to see that $\pi:(\mathscr{E}, \mathscr{H}) \rightarrow(\mathscr{A}, \mathscr{D})$ is a morphism of $\Phi$.

It remains to show that $F(V, k)$ is $\Sigma_{k}$-equivariantly homotopy equivalent to $\mathscr{H}_{V}(k)$ by a map $\phi: F(V, k) \rightarrow \mathscr{H}_{V}(k)$ such that $\pi \phi=\theta$. All the constructions in what follows are easily checked to be equivariant and we shall not mention the point again. It may help the reader to think of $\mathscr{H}_{V}(k)$ as the mapping path space of $\theta$, although this is not quite correct.

We define $\phi$ as follows. Given $\left(v_{1}, \ldots, v_{k}\right)$ in $F(V, k)$, let $\rho$ be

$$
\frac{1}{2} \min \left\{\left\|v_{r}-v_{s}\right\|: r \neq s\right\} \in(0, \infty]
$$

as in Section 3. Then $\phi\left(v_{1}, \ldots, v_{k}\right)$ is to be $\left(h_{1}, \ldots, h_{k}\right)$, where

$$
h_{r}(t)(x)=(1-t)\left(v_{r}+e_{\rho} x\right)+t x \quad \text { for } \quad 0 \leqslant t \leqslant 1 \quad \text { and } \quad x \in V
$$

( $e_{\rho}$ is as in Section 3). From the Lemma we see that the $h_{r}(t)$ are distance-reducing embeddings; and the definition of $e_{\rho}$ shows that $\left\|e_{\rho} x\right\|<\rho$ for all $x$, hence that the $h_{r}(0)$ have disjoint images. It follows that $\left(h_{1}, \ldots, h_{k}\right)$ is in $\mathscr{H}_{V}(k)$. And it is obvious that $\pi \phi=\theta$.

The map homotopy inverse to $\phi$ will be $\psi: \mathscr{H}_{V}(k) \rightarrow F(V, k)$, given by

$$
\psi\left(h_{1}, \ldots, h_{k}\right)=\left(h_{1}(0)(0), \ldots, h_{k}(0)(0)\right)
$$

Clearly $\psi \phi=1$. To construct a homotopy from 1 to $\phi \psi$, let $\left(h_{1}, \ldots, h_{k}\right)$ be a typical point of $\mathscr{H}_{V}(k)$. Write $v_{r}$ for $h_{r}(0)(0)$ and let $\rho \in(0, \infty]$ be

$$
\frac{1}{2} \min \left\{\left\|v_{r}-v_{s}\right\|: r \neq s\right\} .
$$

Then the homotopy $H: \mathscr{H}_{V}(k) \times[0,1] \rightarrow \mathscr{H}_{V}(k)$ from 1 to $\phi \psi$ is to be given by

$$
H\left(h_{1}, \ldots, h_{k} ; \tau\right)=\left(H_{1}(\tau), \ldots, H_{k}(\tau)\right) \quad \text { for } \quad \tau \in[0,1]
$$

where the value of $H_{r}(\tau)(t)$ at a point $x$ of $V$ is as indicated by Figure 1.
To be more precise, Figure 1 shows the value of $H_{r}(\tau)(t)$ for $\tau$ or $t$ equal to 0 or 1 or $\tau=\frac{1}{2}$ or $\tau+t=1$; two formulae are given for diagonal points, which agree because $h_{r}(1)$ is the identity, and the several formulae given for each vertex are also easily seen to agree. The trapezium on the left is filled in by an expression of the form

$$
h_{r}\left(\lambda_{r, t}\right)\left(\alpha_{\tau, t} e_{\rho} x+\left(1-\alpha_{\tau, t}\right) x\right),
$$

where $\lambda$ and $\alpha$ are continuous functions from the trapezium to [ 0,1 ] taking the values given by the figure on the boundary; such functions exist because $[0,1]$ is contractible. Similarly the triangle on the left is filled in by an expression of the form

$$
\alpha_{\tau, t} e_{\rho} x+\left(1-\alpha_{\tau, t}\right) x
$$

with $\alpha$ a continuous function from the triangle to [0,1], the trapezium on the right by an expression of the form

$$
\alpha_{\tau, t} e_{\rho} x+\left(1-\alpha_{\tau, t}\right) x+\kappa_{\tau, t}
$$

with $\alpha$ a continuous function from the trapezium to $[0,1]$ and $\kappa$ a continuous function from the trapezium to $V$ (note that $V$ is contractible), and the triangle on the right by an expression of the form

$$
h_{r}\left(\lambda_{\tau, t}\right)\left(e_{\rho} x\right)+\kappa_{\tau, t}
$$

with $\lambda$ a continuous function from the triangle to $[0,1]$ and $\kappa$ a continuous function from the triangle to $V$.


Fig. 1
Now the Lemma in Section 3 shows that $H_{r}(\tau)(t)$ is always a distance-reducing embedding. For $\tau \geqslant \frac{1}{2}$ we have $\left\|H_{r}(\tau)(0)(x)-v_{r}\right\|<\rho$ for all $x$, since $\left\|e_{\rho} x\right\|<\rho$ and $h_{r}(2 \tau-1)$ is distance-reducing, so the $H_{r}(\tau)(0)$ for fixed $\tau \geqslant \frac{1}{2}$ have disjoint images. The same holds for $\tau \leqslant \frac{1}{2}$, because the $h_{\tau}(0)$ have disjoint images. Therefore the $k$-tuple $\left(H_{1}(\tau), \ldots, H_{k}(\tau)\right)$ is in $\mathscr{H}_{V}(k)$ for all $\tau$ and gives a homotopy from ( $h_{1}, \ldots, h_{k}$ ) to $\phi \psi\left(h_{1}, \ldots, h_{k}\right)$.
This completes the proof.
5. Applications to iterated loop spaces. This section gives the properties which $\mathscr{H}_{V}$ shares with the little cubes operad or the little convex bodies operad. The results are analogous to those in (6), VII•1-2. Some of them are extended from infinite loop spaces to finitely many times iterated loop spaces.

Proposition 1. The functor $V \rightarrow \mathscr{H}_{V}$ is a functor from $\mathscr{I}$ to operads. If $V$ is infinitedimensional, then $\mathscr{H}_{V}$ is an $E_{\infty}$ operad.

Proof. Given the definition of an operad ((3), 1•1 or (6), VI•1•2), one easily verifies the first statement. As for the second, the action of $\Sigma_{k}$ on $\mathscr{H}_{V}(k)$ is clearly free; and $\mathscr{H}_{V}(k)$ is aspherical because

$$
\mathscr{H}_{V}(k)=\operatorname{colim}_{W} \mathscr{H}_{W}(k)
$$

with $W$ running through the finite subspaces of $V$ and the maps involved being closed inclusions (Axiom (2)), so that

$$
\pi_{q} \mathscr{H}_{V}(k) \cong \operatorname{colim}_{W} \pi_{q} \mathscr{H}_{W}(k) \cong \operatorname{colim}_{W} \pi_{q} F(W, k)=0,
$$

since $F(W, k)$ is ( $\operatorname{dim}(W)-2)$-connected ((3), 4•5).
Let $V$ be a finite-dimensional vector space and $S(V)$ be its one-point compactification. If $X$ is a space with base-point, then write $\Omega^{V} X$ for its $V$-fold loop space (that is, the function space $X^{S(V)}$ ) and $\Sigma^{V} X$ for its $V$-fold suspension (that is, the smash product $S(V) \wedge X$ ). Write $Q X$ for colim $\mathscr{W}^{W} \Omega^{W} \Sigma^{W} X$ where $W$ runs through the finite-dimensional subspaces of $\mathbf{R}^{\infty}$, and write $\mathscr{H}_{\infty}$ for $\mathscr{H}_{V}$ with $V=\mathbf{R}^{\infty}$.

Proposition 2. The operads $\mathscr{H}_{V}$ for $V$ finite-dimensional act naturally and compatibly with suspension on $V$-fold loop spaces, and $\mathscr{H}_{\infty}$ acts naturally on the zeroth spaces of spectra.

Here spectrum is taken in the sense of (6), chapter II: it means a coordinate-free strict $\Omega$-spectrum. The proof is like that of (6), VII $\cdot 2 \cdot 1$.

Write $H_{V}$ and $H_{\infty}$ for the monads corresponding to the operads $\mathscr{H}_{V}$ and $\mathscr{H}_{\infty}$ (see (3), $\mathbf{2 . 4}$ ). They behave just like the monads corresponding to the little cubes operads ((3), 4-5); in particular there are canonical maps $\alpha_{V}: H_{V} X \rightarrow \Omega^{V} \Sigma^{V} X$ of $\mathscr{H}_{V}$-spaces for $V$ finite-dimensional and $X$ a based space, and there is also a canonical map

$$
\alpha_{\infty}: H_{\infty} X \rightarrow Q X
$$

of $\mathscr{H}_{\infty}$-spaces.
Proposition 3. The map $\alpha_{V}$ ( $V$ finite-dimensional) is a homeomorphism for $V=\{0\}$ and a group-completion for $\operatorname{dim}(V)$ positive. The map $\alpha_{\infty}$ is a group-completion.

The case $V=\{0\}$ is trivial: $\mathscr{H}_{\{0\}}(0)=*, \mathscr{H}_{\{0\}}(1)=\{1\}$, and $\mathscr{H}_{\{0\}}(k)$ is empty for $k \geqslant 2$, so $H_{\{0\}} X=X$. The case when $V$ is positive-dimensional is given by Segal in (8) and, for $\operatorname{dim}(V) \geqslant 2$, by Cohen in (2), III•3•3. (To say that a map $\alpha: A \rightarrow B$ is a group-completion means at least that $B$ is grouplike and $\alpha$ induces a weak homotopy equivalence of classifying spaces. For $\operatorname{dim}(V) \geqslant 2$ and sometimes also for $\operatorname{dim}(V)=1$ there is an equivalent homological statement; see (1), 3.2, (4), 1 and (7).) For $\alpha_{\infty}$ the result is given by May in (4), 2.2, and there is always an equivalent homological statement.

Write $\mathscr{L}$ for the linear isometries operad ( $(6), \mathrm{I} \cdot 1 \cdot 2$ ).
Proposition 4. With the obvious structure $\left(\mathscr{H}_{\infty}, \mathscr{L}\right)$ is an $E_{\infty}$ operad pair.
This is proved just like (6), VII•2•3.
For $\mathscr{G} \rightarrow \mathscr{L}$ a morphism of operads a $\mathscr{G}$-spectrum is defined as in (6), IV•1•1.
Proposition 5. If there is a morphism $(\mathscr{C}, \mathscr{G}) \rightarrow\left(\mathscr{H}_{\infty}, \mathscr{L}\right)$ of operad pairs, then the zeroth space of a $\mathscr{G}$-spectrum is naturally $a(\mathscr{C}, \mathscr{G})$-space.

This is proved just like (6), VII•2•4.
I am grateful to Peter May for some comments.

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