

Unni Namboodiri Lectures University of Chicago

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Questions raised by our theorem

Our strategy

Abstract: We start by extending the Riemann zeta function from CP^1 (the complex projective line, which is the same thing as the Riemann sphere) to CP^{∞} , the infinite dimensional complex projective space, via multiplication.

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The object is to show that all nontrivial zeros have first coordinate on the critical line.

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The object is to show that all nontrivial zeros have first coordinate on the critical line. The group C_2 acts by complex conjugation. Using the functional equation we can modify the zeta function to get a new function Λ that is symmetric about the critical line. This leads to an action of $G = C_2 \times C_2$ on CP^{∞} for which modified zeta function is equivariant.

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We can extend this function to the complex cobordism spectrum MU (which also gets a *G*-action in this way) by considering higher derivatives of Λ .

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We can extend this function to the complex cobordism spectrum *MU* (which also gets a *G*-action in this way) by considering higher derivatives of Λ . A theorem of Bombieri states that a zero off the critical line leads to an essential map from $CP^{2^i+2^j-1}$ to the fixed point spectrum MU^G , where *i* and *j* depend on the moments of the zero in question.

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Hence the problem is very similar to the Kervaire invariant question except that the group involved is not cyclic.

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Hence the problem is very similar to the Kervaire invariant question except that the group involved is not cyclic. The Slice Theorem (to be explained below) still holds, but the slices themselves are more complicated because of the bigger group.

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Hence the problem is very similar to the Kervaire invariant question except that the group involved is not cyclic. The Slice Theorem (to be explained below) still holds, but the slices themselves are more complicated because of the bigger group. Using the techniques we have developed in the cyclic case, there is a good chance we can do the necessary calculations here and arrive at a similar proof.

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A solution to the Arf-Kervaire invariant problem I: History and background

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Vic Snaith and Bill Browder in 1981 Photo by Clarence Wilkerson

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A wildly popular dance craze



Drawing by Carolyn Snaith 1981 London, Ontario

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Mike Hill, myself and Mike Hopkins Photo taken by Bill Browder February 11, 2010

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Our main theorem can be stated in three different but equivalent ways:



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 Manifold formulation: It says that a certain geometrically defined invariant Φ(M) (the Arf-Kervaire invariant, to be defined later) on certain manifolds M is always zero.

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Our main theorem can be stated in three different but equivalent ways:

- Manifold formulation: It says that a certain geometrically defined invariant Φ(M) (the Arf-Kervaire invariant, to be defined later) on certain manifolds M is always zero.
- Stable homotopy theoretic formulation: It says that certain long sought hypothetical maps between high dimensional spheres do not exist.

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- Unstable homotopy theoretic formulation: It says something about the EHP sequence, which has to do with unstable homotopy groups of spheres.

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The problem solved by our theorem is nearly 50 years old.

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The problem solved by our theorem is nearly 50 years old. There were several unsuccessful attempts to solve it in the 1970s. They were all aimed at proving the opposite of what we have proved.

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Stable Homotopy Around the Arf-Kervaire Invariant, published in early 2009,

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Stable Homotopy Around the Arf-Kervaire Invariant, published in early 2009, just before we proved our theorem.

"As ideas for progress on a particular mathematics problem atrophy it can disappear. Accordingly I wrote this book to stem the tide of oblivion."



"For a brief period overnight we were convinced that we had the method to make all the sought after framed manifolds A solution to the Arf-Kervaire invariant problem Mike Hill

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"For a brief period overnight we were convinced that we had the method to make all the sought after framed manifolds- a feeling which must have been shared by many topologists working on this problem.

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"For a brief period overnight we were convinced that we had the method to make all the sought after framed manifolds- a feeling which must have been shared by many topologists working on this problem. All in all, the temporary high of believing that one had the construction was sufficient to maintain in me at least an enthusiastic spectator's interest in the problem."

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"In the light of the above conjecture and the failure over fifty years to construct framed manifolds of Arf-Kervaire invariant one

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Snaith's book (continued)



"In the light of the above conjecture and the failure over fifty years to construct framed manifolds of Arf-Kervaire invariant one this might turn out to be a book about things which do not exist. This [is] why the quotations which preface each chapter contain a preponderance of utterances from the pen of Lewis Carroll."

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Here is the stable homotopy theoretic formulation.



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Here is the stable homotopy theoretic formulation.

Main Theorem

The Arf-Kervaire elements $\theta_j \in \pi_{2^{j+1}-2+n}(S^n)$ for large *n* do not exist for $j \ge 7$.

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Main Theorem

The Arf-Kervaire elements $\theta_j \in \pi_{2^{j+1}-2+n}(S^n)$ for large *n* do not exist for $j \ge 7$.

The θ_j in the theorem is the name given to a hypothetical map between spheres for which the Arf-Kervaire invariant is nontrivial.

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The θ_j in the theorem is the name given to a hypothetical map between spheres for which the Arf-Kervaire invariant is nontrivial. It follows from Browder's theorem of 1969 that such things can exist only in dimensions that are 2 less than a power of 2.

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Mark Mahowald

Some homotopy theorists, most notably Mahowald, speculated about what would happen if θ_i existed for all *j*.

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Some homotopy theorists, most notably Mahowald, speculated about what would happen if θ_j existed for all *j*. He derived numerous consequences about homotopy groups of spheres.

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Mark Mahowald

Some homotopy theorists, most notably Mahowald, speculated about what would happen if θ_j existed for all *j*. He derived numerous consequences about homotopy groups of spheres. The possible nonexistence of the θ_j for large *j* was known as the Doomsday Hypothesis.

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After 1980, the problem faded into the background because it was thought to be too hard.

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After 1980, the problem faded into the background because it was thought to be too hard. Our proof is two giant steps away from anything that was attempted in the 70s.

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After 1980, the problem faded into the background because it was thought to be too hard. Our proof is two giant steps away from anything that was attempted in the 70s. We now know that the world of homotopy theory is very different from what they had envisioned then.

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Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f: S^{n+k} \rightarrow S^n$ was

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Assume f is smooth.





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• Assume *f* is smooth. We know that any such map is can be continuously deformed to a smooth one.





Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f: S^{n+k} \to S^n$ was

- Assume *f* is smooth. We know that any such map is can be continuously deformed to a smooth one.
- Pick a regular value $y \in S^n$.



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Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f: S^{n+k} \to S^n$ was

- Assume f is smooth. We know that any such map is can be continuously deformed to a smooth one.
- Pick a regular value *y* ∈ *Sⁿ*. Its inverse image will be a smooth *k*-manifold *M* in *S^{n+k}*.

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- Assume f is smooth. We know that any such map is can be continuously deformed to a smooth one.
- Pick a regular value *y* ∈ *Sⁿ*. Its inverse image will be a smooth *k*-manifold *M* in *S^{n+k}*.
- By studying such manifolds, Pontryagin was able to deduce things about maps between spheres.

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Let D^n be the closure of an open ball around a regular value $y \in S^n$.

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Let D^n be the closure of an open ball around a regular value $y \in S^n$. If it is sufficiently small, then $V^{n+k} = f^{-1}(D^n) \subset S^{n+k}$ is an (n + k)-manifold homeomorphic to $M \times D^n$ with boundary homeomorphic to $M \times S^{n-1}$.

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A local coordinate system around around the point $y \in S^n$ pulls back to one around *M* called a framing.

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A local coordinate system around around the point $y \in S^n$ pulls back to one around *M* called a framing.

There is a way to reverse this procedure.

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A local coordinate system around around the point $y \in S^n$ pulls back to one around *M* called a framing.

There is a way to reverse this procedure. A framed manifold $M^k \subset S^{n+k}$ determines a map $f : S^{n+k} \to S^n$.

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To proceed further, we need to be more precise about what we mean by continuous deformation.



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To proceed further, we need to be more precise about what we mean by continuous deformation.

Two maps $f_1, f_2 : S^{n+k} \to S^n$ are homotopic if there is a continuous map $h : S^{n+k} \times [0, 1] \to S^n$ (called a homotopy between f_1 and f_2) such that





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$$h(x,0) = f_1(x)$$
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Here is an example of a framed cobordism for n = k = 1.



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Pontryagin (1930's) M₂ $\Omega_k := \{ stably \ framed \ k-manifolds \} / cobordism$ Theorem: The above construction gives a bijection $\pi_{n+k}(S^n) \approx \Omega_k$ where $\pi_{n+k}(S^n) := \{ \text{maps } S^{n+k} \rightarrow S^n \} /_{\text{homotopy}}$

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Pontryaqin (1930's)

Obstruction: $\phi : H_1(M; \mathbb{Z}/2) \to \mathbb{Z}/2$

Argument: Since the dimension of $H_1(M; \mathbb{Z}/2)$ is even, there is always a non-zero element in the kernel of ϕ , and so surgery can be performed.





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Conclusion: $\Omega_2 = \pi_{n+2}(S^n) = 0.$





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Pontryagin's mistake for k = 2

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Pontryagin's mistake for k = 2

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Tuesday, April 21, 2009

Let λ be a nonsingular anti-symmetric bilinear form on a free abelian group *H* of rank 2*n* with mod 2 reduction \overline{H} .

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In other words, \overline{H} has a basis for which the bilinear form's matrix has the symplectic form

$$\begin{bmatrix} 0 & 1 & & & \\ 1 & 0 & & & \\ & & 0 & 1 & & \\ & & 1 & 0 & & \\ & & & \ddots & & \\ & & & & 0 & 1 \\ 1 & & & & 1 & 0 \end{bmatrix}$$



A quadratic refinement of λ is a map $q:\overline{H} \to \mathbf{Z}/2$ satisfying

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A quadratic refinement of λ is a map $q: \overline{H} \to \mathbf{Z}/2$ satisfying

 $q(x + y) = q(x) + q(y) + \lambda(x, y)$

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In 1941 Arf proved that this invariant (along with the number n) determines the isomorphism type of q.



Money talks: Arf's definition republished in 2009



Cahit Arf 1910-1997

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Let *M* be a 2*m*-connected smooth closed framed manifold of dimension 4m + 2.

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For m = 0, Kervaire's *q* coincides with Pontryagin's φ .

The Kervaire invariant of a framed (4m+2)-manifold (continued)

What can we say about $\Phi(M)$?



The Kervaire invariant of a framed (4m+2)-manifold (continued)

What can we say about $\Phi(M)$?

For m = 0 there is a framing on the torus S¹ × S¹ ⊂ R⁴ with nontrivial Kervaire invariant.



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What can we say about $\Phi(M)$?

• For m = 0 there is a framing on the torus $S^1 \times S^1 \subset \mathbf{R}^4$ with nontrivial Kervaire invariant. Pontryagin used it in 1950 (after some false starts in the 30s) to show $\pi_{n+2}(S^n) = \mathbf{Z}/2$ for all $n \ge 2$.


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More of what we can say about $\Phi(M)$.



More of what we can say about $\Phi(M)$.



Ed Brown



Frank Peterson 1930-2000

Brown-Peterson (1966) showed that it vanishes for all positive even *m*.



Mike Hopkins Doug Ravenel

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Bill Browder

Browder (1969) showed that it can be nontrivial only if $m = 2^{j-1} - 1$ for some positive integer *j*.

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• θ_j is known to exist for $1 \le j \le 5$, i.e., in dimensions 2, 6, 14, 30 and 62.

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- θ_j is known to exist for $1 \le j \le 5$, i.e., in dimensions 2, 6, 14, 30 and 62.
- In the decade following Browder's theorem, many topologists tried without success to construct framed manifolds with nontrivial Kervaire invariant in all dimensions 2 less than a power of 2.

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- Our theorem says θ_j does not exist for j ≥ 7. The case j = 6 is still open.

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Unstable homotopy theoretic formulation.

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Our method of proof offers a new tool, the slice spectral sequence, for studying the stable homotopy groups of spheres.

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Unstable homotopy theoretic formulation. In 1967 Mahowald published an elaborate conjecture about the role of the θ_i (assuming that they all exist) in the unstable homotopy groups of spheres. Since they do not exist, a substitute for his conjecture is needed. We have no idea what it should be.

Our method of proof offers a new tool, the slice spectral sequence, for studying the stable homotopy groups of spheres. We look forward to learning more with it in the future.

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Our proof has several ingredients.



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• We use methods of stable homotopy theory, which means we use spectra instead of topological spaces.



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The slice spectral sequence

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• We use methods of stable homotopy theory, which means we use spectra instead of topological spaces. Roughly speaking, spectra are to spaces as integers are to natural numbers. Instead of making addition formally invertible, we do the same for suspension.

This means

 Every spectrum X is equivalent to the suspension of another spectrum Y = Σ⁻¹X.

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This means

- Every spectrum X is equivalent to the suspension of another spectrum Y = Σ⁻¹X.
- X is equivalent to $\Omega \Sigma X$.
- Fiber sequences and cofiber sequences are the same, up to weak equivalence.

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- Fiber sequences and cofiber sequences are the same, up to weak equivalence.
- While space X has a homotopy group π_k(X) for each positive integer k, a spectrum X has an abelian homotopy group π_k(X) defined for every integer k.

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For the sphere spectrum S^0 , $\pi_k(S^0)$ is the usual homotopy group $\pi_{n+k}(S^n)$ for n > k + 1.

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For the sphere spectrum S^0 , $\pi_k(S^0)$ is the usual homotopy group $\pi_{n+k}(S^n)$ for n > k + 1. The hypothetical θ_j is an element of this group for $k = 2^{j+1} - 2$.

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More ingredients of our proof:

• We use complex cobordism theory.



More ingredients of our proof:

• We use complex cobordism theory. This is a branch of algebraic topology having deep connections with algebraic geometry and number theory.

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More ingredients of our proof:

• We use complex cobordism theory. This is a branch of algebraic topology having deep connections with algebraic geometry and number theory. It includes some highly developed computational techniques that began with work by Milnor, Novikov and Quillen in the 60s.

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John Milnor



Sergei Novikov



Dan Quillen

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More ingredients of our proof:

• We also make use of newer less familiar methods from equivariant stable homotopy theory.



Mike Hill Mike Hopkins Doug Ravenel Anternation Mike Hill Mike Hold Mike Ho

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More ingredients of our proof:

• We also make use of newer less familiar methods from equivariant stable homotopy theory. This means there is a finite group *G* (a cyclic 2-group) acting on all spaces in sight, and all maps are required to commute with these actions.

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• We also make use of newer less familiar methods from equivariant stable homotopy theory. This means there is a finite group *G* (a cyclic 2-group) acting on all spaces in sight, and all maps are required to commute with these actions. When we pass to spectra, we get homotopy groups indexed not just by the integers **Z**, but by *RO*(*G*), the real representation ring of *G*.

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Peter May



John Greenlees



Gaunce Lewis 1949-2006

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We will produce a map $S^0 \rightarrow \Omega$, where Ω is a nonconnective spectrum (meaning that it has nontrivial homotopy groups in arbitrarily large negative dimensions) with the following properties.

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We will produce a map $S^0 \rightarrow \Omega$, where Ω is a nonconnective spectrum (meaning that it has nontrivial homotopy groups in arbitrarily large negative dimensions) with the following properties.

(i) Detection Theorem. It has an Adams-Novikov spectral sequence (which is a device for calculating homotopy groups) in which the image of each θ_i is nontrivial.

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- (ii) Periodicity Theorem. It is 256-periodic, meaning that $\pi_k(\Omega)$ depends only on the reduction of *k* modulo 256.

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- (ii) Periodicity Theorem. It is 256-periodic, meaning that $\pi_k(\Omega)$ depends only on the reduction of *k* modulo 256.
- (iii) Gap Theorem. $\pi_k(\Omega) = 0$ for -4 < k < 0.

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- (iii) Gap Theorem. $\pi_k(\Omega) = 0$ for -4 < k < 0. This property is our zinger. Its proof involves a new tool we call the slice spectral sequence.

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- (iii) Gap Theorem. $\pi_{-2}(\Omega) = 0$.

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- (ii) Periodicity Theorem. $\pi_k(\Omega)$ depends only on the reduction of *k* modulo 256.
- (iii) Gap Theorem. $\pi_{-2}(\Omega) = 0$.

(ii) and (iii) imply that $\pi_{254}(\Omega) = 0$.

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(ii) and (iii) imply that $\pi_{254}(\Omega) = 0$.

If $\theta_7 \in \pi_{254}(S^0)$ exists, (i) implies it has a nontrivial image in this group, so it cannot exist.

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(ii) and (iii) imply that $\pi_{254}(\Omega) = 0$.

If $\theta_7 \in \pi_{254}(S^0)$ exists, (i) implies it has a nontrivial image in this group, so it cannot exist. The argument for θ_j for larger *j* is similar, since $|\theta_j| = 2^{j+1} - 2 \equiv -2 \mod 256$ for $j \geq 7$.

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Our spectrum Ω will be the fixed point spectrum for the action of C_8 (the cyclic group of order 8) on an equivariant spectrum $\tilde{\Omega}$.

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To construct it we start with the complex cobordism spectrum *MU*.

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To construct it we start with the complex cobordism spectrum MU. It can be thought of as the set of complex points of an algebraic variety defined over the real numbers. This means that it has an action of C_2 defined by complex conjugation.

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To construct it we start with the complex cobordism spectrum MU. It can be thought of as the set of complex points of an algebraic variety defined over the real numbers. This means that it has an action of C_2 defined by complex conjugation. The fixed point set of this action is the set of real points, known to topologists as MO, the unoriented cobordism spectrum.

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Some people who have studied MU as a C_2 -spectrum:

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Shoro Araki 1930–2005

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Igor Kriz and Po Hu

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Igor Kriz and Po Hu



Shoro Araki 1930–2005



Nitu Kitchloo



Steve Wilson

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To get a C_8 -spectrum, we use the following general construction for getting from a space or spectrum X acted on by a group H to one acted on by a larger group G containing H as a subgroup.

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Mike Hopkins

Doug Ravenel

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To get a C_8 -spectrum, we use the following general construction for getting from a space or spectrum *X* acted on by a group *H* to one acted on by a larger group *G* containing *H* as a subgroup. Let

 $Y = \operatorname{Map}_{H}(G, X),$

the space (or spectrum) of H-equivariant maps from G to X.

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$$Y = \mathsf{Map}_H(G, X)$$

the space (or spectrum) of H-equivariant maps from G to X. Here the action of H on G is by left multiplication, and the resulting object has an action of G by left multiplication.

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the space (or spectrum) of *H*-equivariant maps from *G* to *X*. Here the action of *H* on *G* is by left multiplication, and the resulting object has an action of *G* by left multiplication. As a set, $Y = X^{|G/H|}$, the |G/H|-fold Cartesian power of *X*.

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 $Y = \operatorname{Map}_{H}(G, X),$

the space (or spectrum) of *H*-equivariant maps from *G* to *X*. Here the action of *H* on *G* is by left multiplication, and the resulting object has an action of *G* by left multiplication. As a set, $Y = X^{|G/H|}$, the |G/H|-fold Cartesian power of *X*. A general element of *G* permutes these factors, each of which is invariant under the action of the subgroup *H*.

In particular we get a C₈-spectrum

$$MU_{\mathbf{R}}^{(4)} = \operatorname{Map}_{C_2}(C_8, MU_{\mathbf{R}}).$$

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To get a C_8 -spectrum, we use the following general construction for getting from a space or spectrum *X* acted on by a group *H* to one acted on by a larger group *G* containing *H* as a subgroup. Let

 $Y = \operatorname{Map}_{H}(G, X),$

the space (or spectrum) of *H*-equivariant maps from *G* to *X*. Here the action of *H* on *G* is by left multiplication, and the resulting object has an action of *G* by left multiplication. As a set, $Y = X^{|G/H|}$, the |G/H|-fold Cartesian power of *X*. A general element of *G* permutes these factors, each of which is invariant under the action of the subgroup *H*.

In particular we get a C₈-spectrum

$$MU_{\mathbf{R}}^{(4)} = \operatorname{Map}_{C_2}(C_8, MU_{\mathbf{R}}).$$

This spectrum is not periodic, but it has a close relative $\tilde{\Omega}$ which is.

A solution to the Arf-Kervaire invariant problem Mike Hill



Pontryagin's early work The Arf-Kervaire formulation

Questions raised by our theorem

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A homotopy fixed point spectral sequence



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Mike Hopkins

Doug Ravenel



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The corresponding slice spectral sequence



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