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What is an ∞ -category?



Image appearing in an article by Emily Riehl

in Scientific American, October 2021

Doug Ravenel University of Rochester

4 August, 2023

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This is an expository talk on ∞ -categories.

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We will adhere to the following color convention:

• Ordinary categories will be written in green.

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We will adhere to the following color convention:

- Ordinary categories will be written in green.
- ∞-categories (that are not ordinary categories) will be written in lilac.

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 For objects W, X and Y in an ordinary category C, one has a morphism sets C(X, Y), C(W, Y) and C(W, X), What is an ∞ -category? Doug Ravenel

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$$C(X, Y) \times C(W, X) \longrightarrow C(W, Y)$$

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$$(a, f) \longmapsto af.$$

In an ∞ -category C, these three sets are topological spaces or simplicial sets, specifically Kan complexes.

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 Many definitions involve weak equivalences of morphism spaces rather than isomorphisms of morphism sets.

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 Many definitions involve weak equivalences of morphism spaces rather than isomorphisms of morphism sets. For example, an initial object X in C is one for which C(X, Y) is contractible for all Y.

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- Many definitions involve weak equivalences of morphism spaces rather than isomorphisms of morphism sets. For example, an initial object X in C is one for which C(X, Y) is contractible for all Y.
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- An ∞-category is a certain kind of simplicial set (but not generally a Kan complex), so it is sort of like a topological space. There is a model structure on the category of simplicial sets due to Joyal

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Introduction (continued)

- Many definitions involve weak equivalences of morphism spaces rather than isomorphisms of morphism sets. For example, an initial object X in C is one for which C(X, Y) is contractible for all Y.
- In an ∞-category, homotopy limits/colimits are the same as ordinary limits/colimits when they exist.
- In an ∞-category one need not worry about a model structure, but concepts of model category theory are needed to develop the theory of ∞-categories.
- An ∞-category is a certain kind of simplicial set (but not generally a Kan complex), so it is sort of like a topological space. There is a model structure on the category of simplicial sets due to Joyal in which the fibrant objects are the ∞-categories.

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The simplicial category Δ is that of finite ordered sets and order preserving maps.

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 the order preserving monomorphism [k − 1] → [k] whose image does not contain i

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- the order preserving monomorphism [k − 1] → [k] whose image does not contain i and
- the order preserving epimorphism [k + 1] → [k] sending both *i* and *i* + 1 to *i*.

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The simplicial set Δ^n , the standard *n*-simplex, is defined by

 $(\Delta^n)_k = \Delta([k], [n]).$

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In its boundary $\partial \Delta^n$, the set of *k*-simplices is the set of such morphisms in Δ which are not surjective.

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In its *i*th face, the set of *k*-simplices is the set of such morphisms whose image does not contain *i*.

In the *i*th horn $\Lambda_i^n \subseteq \partial \Delta^n$ for $0 \le i \le n$, the set of *k*-simplices is the set of nonsurjective morphisms whose image does contain *i*.

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In the *i*th horn $\Lambda_i^n \subseteq \partial \Delta^n$ for $0 \le i \le n$, the set of *k*-simplices is the set of nonsurjective morphisms whose image does contain *i*.

The inner faces and horns are those for which 0 < i < n.

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Here are the three horns of a 2-simplex.

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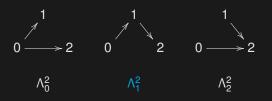
In the *i*th horn, the missing face is opposite the *i*th vertex.

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Here are the three horns of a 2-simplex.



In the *i*th horn, the missing face is opposite the *i*th vertex.

A Kan complex is a simplicial set *X* for which every map from a horn $\Lambda_i^n \to X$ extends to Δ^n .

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The topological *n*-simplex Δ_{top}^n is the space



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$$\left\{(x_0, x_1, \ldots, x_n) \in \mathbb{R}^{n+1} : x_i \ge 0 \text{ and } \sum x_i = 1\right\}.$$

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The geometric realization |X| of a simplicial set X is the colimit of the Top-valued functor

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$$(X \times Y)_n = \prod_{0 \le i \le n} X_i \times Y_{n-i}$$
 and $|X \times Y| = |X| \times |Y|$.

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The category of simplicial sets is denoted by Set_{Δ} .

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 and $|X \times Y| = |X| \times |Y|$.

The category of simplicial sets is denoted by Set_{Δ} .

A simplicial map $X \to Y$ is a natural transformation of contravariant functors on Δ . The set of such maps is $Set_{\Delta}(X, Y)$. This can be thickened up to a simplicial set $Set_{\Delta}(X, Y)$ in which the set of *k*-simplices is $Set_{\Delta}(X \times \Delta^k, Y)$.

Hence $\mathcal{S}et_{\Delta}$ is enriched over itself.

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$$X_0 o X_1 o \cdots o X_n$$

in C.

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 $X_0 \rightarrow X_1 \rightarrow \cdots \rightarrow X_n$

in *C*. Face and degeneracy maps are defined by composing adjacent morphisms and inserting identity maps.

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 $X_0 \rightarrow X_1 \rightarrow \cdots \rightarrow X_n$

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in *C*. Face and degeneracy maps are defined by composing adjacent morphisms and inserting identity maps. Equivalently we can regard [n] as the category

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and define NC_n to be the set of functors from [n] to C.

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This simplicial set has the following property: Any simplicial map $\Lambda_i^n \to NC$ for 0 < i < n extends uniquely to Δ^n .

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It is known that the category C is determined by its nerve, and that any simplicial set with property above is the nerve of some small category.

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It is known that the category C is determined by its nerve, and that any simplicial set with property above is the nerve of some small category.

A small category is thus equivalent to a simplicial set (its nerve) in which each map from an inner horn Λ_i^n extends uniquely to a map from Δ^n .

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There are several features of this definition worth noting.

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 We are not requiring extensions of maps from Λ₀ⁿ and Λ_nⁿ (known as the left and right outer horns) as in the definition of a Kan complex.

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- The extension of each map from an inner horn is not required to be unique, as it is in the nerve of an ordinary category. This means that this notion is more general than that of an ordinary category as seen through its nerve. Hence an ordinary category is a special case of an ∞-category.

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 Given such a simplicial set C, we can think of elements of the sets C₀ and C₁ as objects and morphisms.

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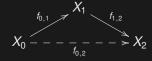
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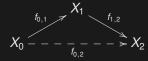
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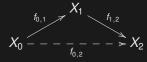
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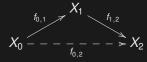
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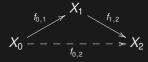
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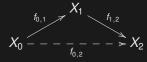
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The simplicial set Set_△(K, D) of simplicial maps from a simplicial set K to an ∞-category D is itself an ∞-category.

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- *K* itself could be an ∞ -category C,

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Definition

An ∞ -category (also called a quasicategory) C is a simplicial set in which each simplicial map $\Lambda_i^n \to C$ for 0 < i < n extends to some map $\Delta^n \to C$. A functor $F : C \to C'$ from one ∞ -category to another is a simplicial map.

- The simplicial set Set_△(K, D) of simplicial maps from a simplicial set K to an ∞-category D is itself an ∞-category.
- K itself could be an ∞-category C, in particular it could be NC for an ordinary category C.

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- The simplicial set Set_△(K, D) of simplicial maps from a simplicial set K to an ∞-category D is itself an ∞-category.
- *K* itself could be an ∞-category *C*, in particular it could be *NC* for an ordinary category *C*. In other words, the collection of functors *C* → *D* is an ∞-category Fun(*C*, *D*).

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To a topological space X we can associate an ∞ -category X (also known as Sing X, the singular simplicial set of X)

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Such an $\infty\text{-category}$ is called an $\infty\text{-groupoid}$

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Such an ∞ -category is called an ∞ -groupoid because all morphisms, i.e., paths in *X*, are invertible up to homotopy.

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Lurie's S is actually the homotopy coherent nerve of the category \mathcal{K} an of Kan complexes,

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As in our main definition, $\ensuremath{\mathcal{S}}$ is a simplicial set.

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As in our main definition, S is a simplicial set. Its vertices and edges are objects and morphisms in Top, meaning spaces and continuous maps.

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The set of 2-simplices is more interesting. In the subcategory NTop (the ordinary nerve), it is the set of commutative diagrams of the form



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The top two edges can be viewed as a map $\Lambda_2^1 \rightarrow N$ Top,

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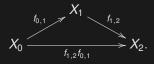
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NTop₂ is the set of commutative diagrams of the form



The set of 2-simplices S_2 consists of similar diagrams

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The set of 2-simplices S_2 consists of similar diagrams in which the bottom arrow is replaced by any map $f_{0,2}$ homotopic to $f_{1,2}f_{0,1}$, with the homotopy $h_{0,2}$ being part of the datum.

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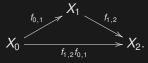
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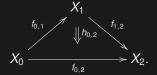
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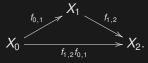
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The homotopy $h_{0,2}$ is a map $I \times X_0 \rightarrow X_2$ with certain properties.

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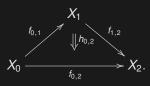
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The homotopy is a map



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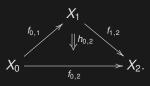
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The homotopy is a map

$$I \times X_0 \xrightarrow{h_{0,2}} X_2$$

with certain properties. It is adjoint to a path (which we denote by the same symbol)

$$I \xrightarrow{h_{0,2}} \operatorname{Top}(X_0, X_2)$$
$$0 \longmapsto f_{1,2}f_{0,1}$$
$$1 \longmapsto f_{0,2}$$

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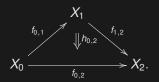
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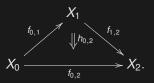
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$X_{0} \xrightarrow{f_{0,1}} V_{1} \xrightarrow{f_{1,2}} X_{2}.$

As in the ordinary case, the top two edges of the diagram can be viewed as a map $\Lambda_1^2 \to S$. Now there is an extension of it to Δ^2 for each path $h_{0,2}$ in Top(X_0, X_2) starting at the point $f_{1,2}f_{0,1}$.

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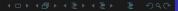
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The following diagram shows four 2-simplices with their homotopies.

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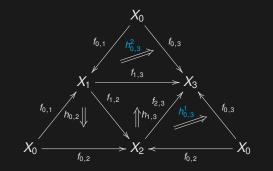
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The following diagram shows four 2-simplices with their homotopies.



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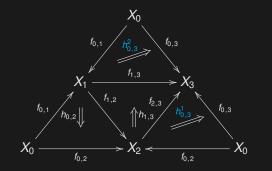
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The following diagram shows four 2-simplices with their homotopies.

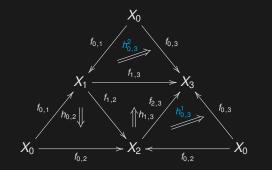


This is the boundary of a 3-simplex in \mathcal{S} iff there is a certain double homotopy

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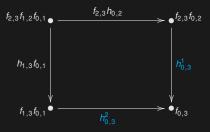
The following diagram shows four 2-simplices with their homotopies.



This is the boundary of a 3-simplex in S iff there is a certain double homotopy adjoint to a map $h_{0,3} : l^2 \to \text{Top}(X_0, X_3)$ shown on the next slide.

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The diagram on the previous is the boundary of a 3-simplex in S iff there a map $h_{0,3}: l^2 \to \text{Top}(X_0, X_3)$ of the form



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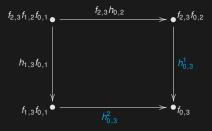
 $\begin{array}{l} \text{The set } \mathcal{S}_{n+1} \text{ for} \\ n > 3 \end{array}$

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The diagram on the previous is the boundary of a 3-simplex in S iff there a map $h_{0,3}: l^2 \to \text{Top}(X_0, X_3)$ of the form

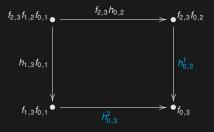


This is a picture rather than a diagram.

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The diagram on the previous is the boundary of a 3-simplex in S iff there a map $h_{0,3}: l^2 \to \text{Top}(X_0, X_3)$ of the form



This is a picture rather than a diagram. Each vertex of the square is a point in $\text{Top}(X_0, X_3)$, while the upper and left edges are the indicated compsites.

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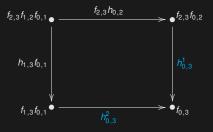
 $\begin{array}{l} \text{The set } \mathcal{S}_{n+1} \text{ for} \\ n > 3 \end{array}$

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The diagram on the previous is the boundary of a 3-simplex in S iff there a map $h_{0,3}: l^2 \to \text{Top}(X_0, X_3)$ of the form



This is a picture rather than a diagram. Each vertex of the square is a point in $Top(X_0, X_3)$, while the upper and left edges are the indicated compsites. The other edges are the homotopies shown in the previous slide.

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For each 4-simplex, the additional datum is a map $h_{0,4}: l^3 \to \text{Top}(X_0, X_4)$ of the form

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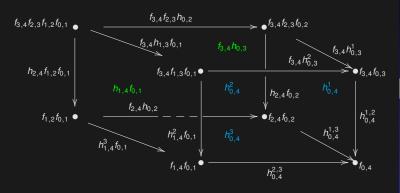
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For each 4-simplex, the additional datum is a map $h_{0,4}: I^3 \to \text{Top}(X_0, X_4)$ of the form



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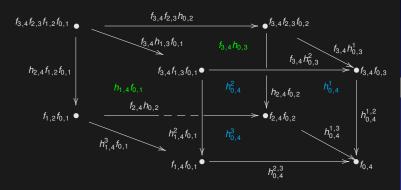
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For each 4-simplex, the additional datum is a map $h_{0,4}: I^3 \to \text{Top}(X_0, X_4)$ of the form



The restriction of $h_{0,4}$ to the left and top faces are the composite double homotopies indicated in green.

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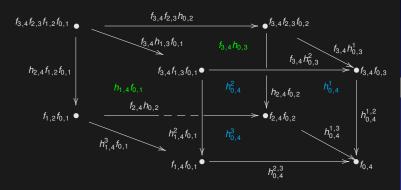
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For each 4-simplex, the additional datum is a map $h_{0,4}: I^3 \to \text{Top}(X_0, X_4)$ of the form



The restriction of $h_{0,4}$ to the left and top faces are the composite double homotopies indicated in green. The restrictions to the three faces abuting $f_{0,4}$ are double homotopies indicated in blue.

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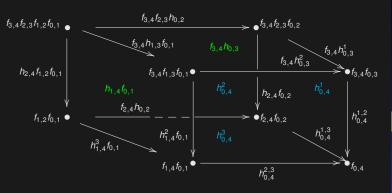
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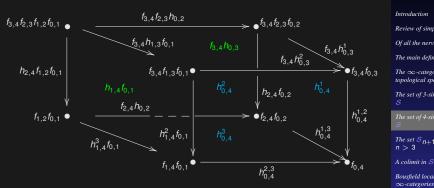
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The restriction of $h_{0.4}$ to the back face (not labeled) is the composite

$$I \times I \xrightarrow{h_{2,4} \times h_{0,2}} \operatorname{Top}(X_2, X_4) \times \operatorname{Top}(X_0, X_2)$$

$$\downarrow^{\operatorname{comp}} \operatorname{Top}(X_0, X_4).$$

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The five labeled faces are associated with the five 3-dimensional faces of the corresponding 4-simplex in S.

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For each (n + 1)-simplex there is a sequence of spaces and continuous maps

$$X_0 \xrightarrow{f_{0,1}} X_1 \xrightarrow{f_{1,2}} \cdots \xrightarrow{f_{n,n+1}} X_{n+1}$$

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For each (n + 1)-simplex there is a sequence of spaces and continuous maps

$$X_0 \xrightarrow{f_{0,1}} X_1 \xrightarrow{f_{1,2}} \cdots \xrightarrow{f_{n,n+1}} X_{n+1}$$

and a map

$$I^{n} \xrightarrow{h_{0,n}} \operatorname{Top}(X_{0}, X_{n+1})$$

$$(0, \dots, 0) \longmapsto f_{n,n+1} \cdots f_{0,1}$$

$$(1, \dots, 1) \longmapsto f_{0,n+1}$$

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$$(0, \dots, 0) \longmapsto f_{n,n+1} \cdots f_{0,1}$$

$$(1, \dots, 1) \longmapsto f_{0,n+1}$$

We refer to these two points as the left and right vertices of the *n*-cube,

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We refer to these two points as the left and right vertices of the *n*-cube, and the *n* faces meeting each of them as the left and right faces.

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For each (n + 1)-simplex there is a sequence of spaces and continuous maps

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The n + 2 faces of the associated (n + 1)-simplex correspond to the *n* right faces of this cube,

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The n + 2 faces of the associated (n + 1)-simplex correspond to the *n* right faces of this cube, along with the two left faces

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$$(0, \dots, 0) \longmapsto f_{n,n+1} \cdots f_{0,1}$$

$$(1, \dots, 1) \longmapsto f_{0,n+1}$$

We refer to these two points as the left and right vertices of the *n*-cube, and the *n* faces meeting each of them as the left and right faces.

The n + 2 faces of the associated (n + 1)-simplex correspond to the *n* right faces of this cube, along with the two left faces

 $\{(t_1,\ldots,t_{n-1},0)\}$ and $\{(0,t_2,\ldots,t_n)\}.$

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To sum up, the ∞ -category \mathcal{S} of topological spaces is a simplicial set in which

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To sum up, the $\infty\text{-category }\mathcal{S}$ of topological spaces is a simplicial set in which

• there is a vertex for each topological space in Top,

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To sum up, the $\infty\text{-category }\mathcal{S}$ of topological spaces is a simplicial set in which

- there is a vertex for each topological space in Top,
- there is an edge for each continuous map, and

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To sum up, the $\infty\text{-category }\mathcal{S}$ of topological spaces is a simplicial set in which

- there is a vertex for each topological space in Top,
- there is an edge for each continuous map, and
- for n > 0, there is an (n + 1)-simplex for each sequence of spaces and continuous maps

$$X_0 \xrightarrow{f_0} X_1 \xrightarrow{f_1} \cdots \xrightarrow{f_n} X_{n+1}$$
 and

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To sum up, the $\infty\text{-category }\mathcal{S}$ of topological spaces is a simplicial set in which

- there is a vertex for each topological space in Top,
- there is an edge for each continuous map, and
- for n > 0, there is an (n + 1)-simplex for each sequence of spaces and continuous maps

$$X_0 \xrightarrow{f_0} X_1 \xrightarrow{f_1} \cdots \xrightarrow{f_n} X_{n+1}$$
 and

• each map $h_n : I^n \to \text{Top}(X_0, X_{n+1})$ meeting certain boundary conditions described above.

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To sum up, the $\infty\text{-category }\mathcal{S}$ of topological spaces is a simplicial set in which

- there is a vertex for each topological space in Top,
- there is an edge for each continuous map, and
- for n > 0, there is an (n + 1)-simplex for each sequence of spaces and continuous maps

$$X_0 \xrightarrow{f_0} X_1 \xrightarrow{f_1} \cdots \xrightarrow{f_n} X_{n+1}$$
 and

• each map $h_n : I^n \to \text{Top}(X_0, X_{n+1})$ meeting certain boundary conditions described above.

To repeat, there is an (n + 1)-simplex for every suitable datum.

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To sum up, the $\infty\text{-category }\mathcal{S}$ of topological spaces is a simplicial set in which

- there is a vertex for each topological space in Top,
- there is an edge for each continuous map, and
- for n > 0, there is an (n + 1)-simplex for each sequence of spaces and continuous maps

$$X_0 \xrightarrow{f_0} X_1 \xrightarrow{f_1} \cdots \xrightarrow{f_n} X_{n+1}$$
 and

• each map $h_n : I^n \to \text{Top}(X_0, X_{n+1})$ meeting certain boundary conditions described above.

To repeat, there is an (n + 1)-simplex for every suitable datum. This construction does not require any choices.

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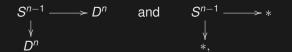
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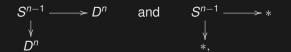
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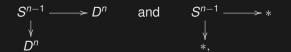
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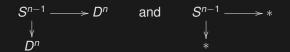
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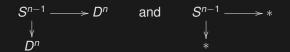
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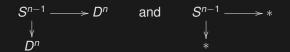
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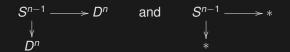
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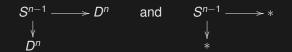
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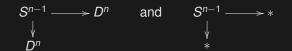
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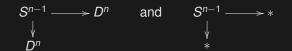
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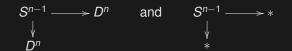
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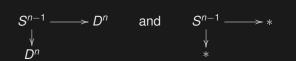
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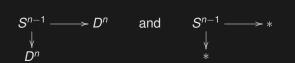
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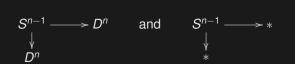
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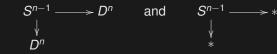
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Let *p* be the diagram on the right.

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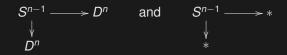
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Let *p* be the diagram on the right. We are looking for an initial object in $S_{/p}$.

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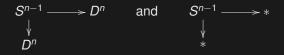
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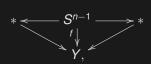
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Let *p* be the diagram on the right. We are looking for an initial object in $S_{/p}$. An object in $S_{/p}$ is a diagram



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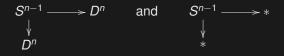
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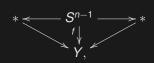
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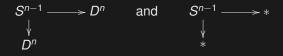
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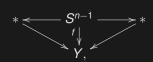
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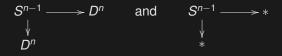
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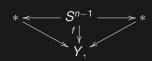
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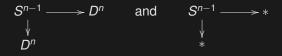
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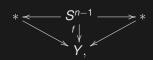
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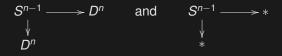
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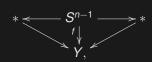
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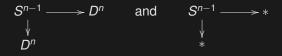
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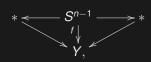
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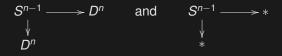
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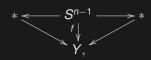
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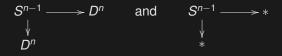
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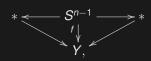
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More details can be found in [HTT, 4.2.4].

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IMHO, Bousfield localization is the best construction in model category theory. One starts with a model category \mathcal{M} , and enlarges the class of weak equivalences in some way without altering the class of cofibrations.

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Under mild hypotheses on \mathcal{M} ,

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Under mild hypotheses on \mathcal{M} , but none on how we enlarge the class of weak equivalences,

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Under mild hypotheses on \mathcal{M} , but none on how we enlarge the class of weak equivalences, this leads to a new model structure with a much more interesting fibrant replacement functor *L*.

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Under mild hypotheses on \mathcal{M} , but none on how we enlarge the class of weak equivalences, this leads to a new model structure with a much more interesting fibrant replacement functor *L*.

When we enlarge the class of weak equivalences (in the category of spaces or spectra)

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Under mild hypotheses on \mathcal{M} , but none on how we enlarge the class of weak equivalences, this leads to a new model structure with a much more interesting fibrant replacement functor *L*.

When we enlarge the class of weak equivalences (in the category of spaces or spectra) to those maps inducing an isomorphism in Morava *E*-theory (or Morava *K*-theory) for a fixed prime p and height n,

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When we enlarge the class of weak equivalences (in the category of spaces or spectra) to those maps inducing an isomorphism in Morava *E*-theory (or Morava *K*-theory) for a fixed prime *p* and height *n*, this fibrant replacement functor is the L_n (or $L_{K(n)}$) of chromatic homotopy theory.

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Bousfield localization in ∞ -categories (continued)

[HTT, Proposition 5.5.4.15] is statement about an analog of Bousfield localization. The input is a presentable ∞ -category C with a set of morphisms *S* that are meant to be made into weak equivalences.

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Bousfield localization in ∞ -categories (continued)

[HTT, Proposition 5.5.4.15] is statement about an analog of Bousfield localization. The input is a presentable ∞ -category C with a set of morphisms *S* that are meant to be made into weak equivalences. Presentable means that C has small colimits

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In [HTT, Definition 5.5.4.1] an object *Z* is said to be *S*-local if each morphism $s : X \to Y$ in *S* induces a homotopy equivalence $C(Y, Z) \to C(X, Z)$.

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Let \overline{S} be the set of all *S*-equivalences.

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Let \overline{S} be the set of all *S*-equivalences. It can be explicitly constructed from *S*.

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Let \overline{S} be the set of all S-equivalences. It can be explicitly constructed from S. Let C' be the full subcategory of S-local objects. Then

● For each object X ∈ C, there exists a morphism s : X → X' such that X' is S-local and s belongs to S.

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● For each object X ∈ C, there exists a morphism s : X → X' such that X' is S-local and s belongs to S.

2 The ∞ -category \mathcal{C}' is presentable.



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● For each object X ∈ C, there exists a morphism s : X → X' such that X' is S-local and s belongs to S.

2 The ∞ -category \mathcal{C}' is presentable.

3 The inclusion functor $C' \subseteq C$ has a left adjoint *L*.

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Let \overline{S} be the set of all S-equivalences. It can be explicitly constructed from S. Let C' be the full subcategory of S-local objects. Then

For each object X ∈ C, there exists a morphism s : X → X'
 such that X' is S-local and s belongs to S.

2 The ∞ -category \mathcal{C}' is presentable.

The inclusion functor C' ⊆ C has a left adjoint L. This is the analog of Bousfield's fibrant replacement functor in model category theory.

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• Pass to \mathcal{S}_* , the ∞ -category of pointed spaces.

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 Pass to S_{*}, the ∞-category of pointed spaces. This is straightforward.

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- S_{*} has a loop functor Ω, leading to a tower

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• Then Sp is the homotopy limit of this tower,

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- S_{*} has a loop functor Ω, leading to a tower

$$\cdots \xrightarrow{\Omega} \mathcal{S}_* \xrightarrow{\Omega} \mathcal{S}_* \xrightarrow{\Omega} \mathcal{S}_*$$

of ∞ -categories and functors.

• Then Sp is the homotopy limit of this tower, which is the same as the limit in the ∞ -category of ∞ -categories.

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Sp is the homotopy limit of the tower

$$\cdots \xrightarrow{\Omega} \mathcal{S}_* \xrightarrow{\Omega} \mathcal{S}_* \xrightarrow{\Omega} \mathcal{S}_* \xrightarrow{\Omega} \mathcal{S}_*$$
$$X_2 \qquad X_1 \qquad X_0$$

To unpack this definition, note that a vertex in this homotopy limit (meaning an object in the ∞ -category Sp) consists of a sequence of pointed spaces X_0, X_1, X_2, \ldots ,

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Sp is the homotopy limit of the tower

$$\cdots \xrightarrow{\Omega} S_* \xrightarrow{\Omega} S_* \xrightarrow{\Omega} S_* \xrightarrow{\Omega} S_*$$
$$X_2 \qquad X_1 \qquad X_0$$

To unpack this definition, note that a vertex in this homotopy limit (meaning an object in the ∞ -category Sp) consists of a sequence of pointed spaces X_0, X_1, X_2, \ldots , along with weak equivalences $X_i \rightarrow \Omega X_{i+1}$.

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Sp is the homotopy limit of the tower

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$$X_2 \qquad X_1 \qquad X_0$$

To unpack this definition, note that a vertex in this homotopy limit (meaning an object in the ∞ -category Sp) consists of a sequence of pointed spaces X_0, X_1, X_2, \ldots , along with weak equivalences $X_i \rightarrow \Omega X_{i+1}$. This coincides with the original definition of an Ω -spectrum.

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The ∞ -category Sp satisfies the following, which is [HA, Definition 1.1.1.9].

Definition

An ∞ -category \mathcal{C} is stable if

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The ∞ -category Sp satisfies the following, which is [HA, Definition 1.1.1.9].

Definition

An ∞ -category $\mathcal C$ is stable if

- 🥑 It is pointed.
- Por each morphism f : X → Y there are pullback and pushout diagrams







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the fiber and cofiber sequences of f.

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the fiber and cofiber sequences of f.

A diagram of the above form is a pushout if and only if it is a pullback,

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Definition

- An ∞ -category \mathcal{C} is stable if
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 - Por each morphism f : X → Y there are pullback and pushout diagrams



the fiber and cofiber sequences of f.

A diagram of the above form is a pushout if and only if it is a pullback, i.e., fiber sequences and cofiber sequences are the same.

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